



Introduction

- Anomaly detection (AD) aims to identify defective images and localize the defects.
- Fig. 1 shows that AD models should be able to detect defects over many image classes,
 - without relying on hard-coded class names that can be uninformative.
 - learn without anomaly supervision.
 - robust to the long-tailed distributions of real-world applications.
- To address these challenges, we formulate the problem of long-tailed AD by introducing several datasets split with different levels of class imbalance.
- A novel method, LTAD, is proposed to detect defects from multiple and long-tailed classes, without relying on dataset class names.

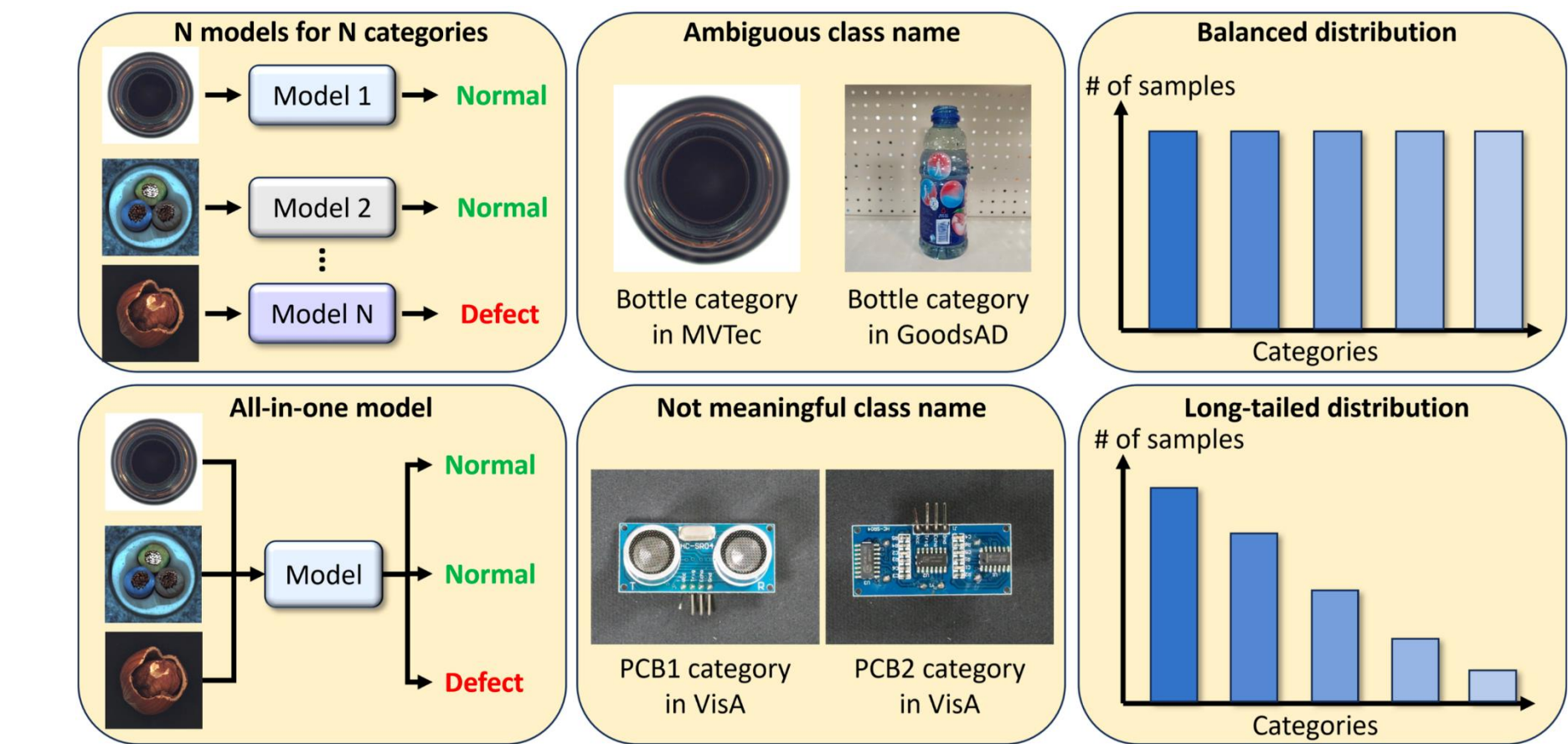


Fig 1. Challenges of long-tailed AD include (Left) designing a single model to detect anomalies over multiple image classes, (Middle) uninformative class names, and (Right) long-tailed data distributions.

Dataset Split & Preliminary Study

- To study how long-tailed distribution affect the performance, we first proposed several new long-tail dataset splits, as shown in left of Fig. 2
 - Imbalance type (e.g. exponential decay and step decay)
 - Class imbalance factor $\beta = \frac{\max\{N_c\}}{\min\{N_c\}}$, where N_c is the sample number of class c
- Performance degrades as the number of sample decreases (See the right of Fig. 2).

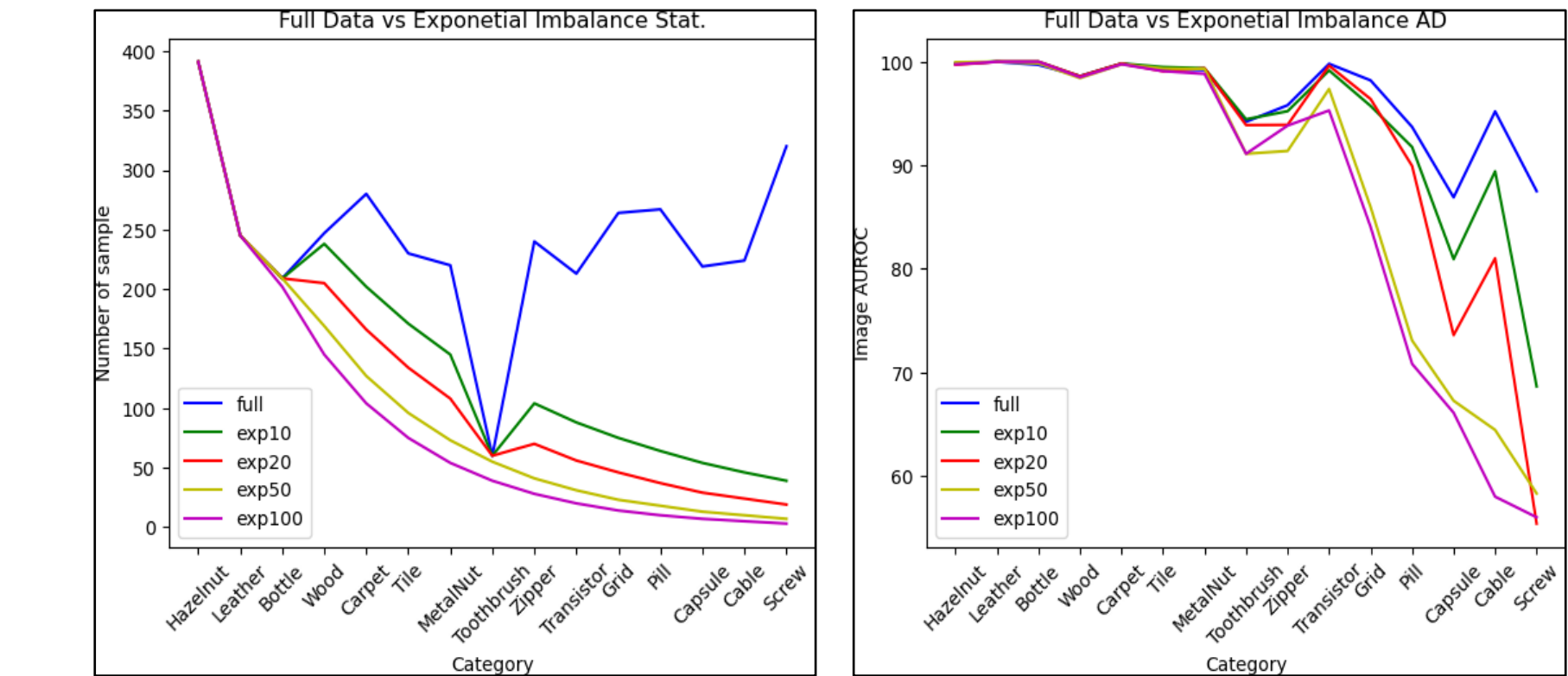


Fig 2. Image classes (x-axis) are sorted by popularity. (Left) Dataset distribution of MVTEC [1] vs. long-tailed version. (Right) AD performance of UniAD [2] on the two datasets.

Proposed Method

Training

- The proposed training pipeline, LTAD, contains 2 phases
 - Phase 1: Learn to synthesize feature for tail classes
 - Phase 2: Train to predict the anomaly map using the real/synthesized feature
- For implementation, we use the pretrained visual-language model ALIGN [3], which contains a text encoder and an image encoder that align the image and text to the same feature space.

Phase 1: Class sensitive data augmentation

- Goal: Learn to synthesize feature for tail classes.
- With ALIGN, we proposed a text conditional VAE for synthesizing features (top of Fig. 3).
- Since the class name is **unknown**, a pseudo class name s_c is learned for each category c .
- MSE loss minimizes reconstruction difference of encoder/decoder feature.
- KL divergence loss regularizes the latent distribution.

Phase 2: Anomaly Detection

- Goal: Train to predict the anomaly map using the real/synthesized feature.
- Phase 2 takes normal feature p_i^n as input (i.e. Real feature or synthesized feature from phase 1).
- Since only normal patch feature p_i^n is available during training, noise is added to the normal feature to create abnormal feature p_i^a .
- Phase 2 contains 2 submodules, including the semantic AD (SAD) module (top of Fig. 3 phase 2) and the reconstruction module (RM) (bottom of Fig. 3 phase 2).
- Reconstruction module (RM)**
 - Maps the input feature to normal feature and the MSE loss is used to minimize $\|p_i^n - RM(p_i^n)\|_2^2$ during training.
- Semantic AD (SAD) module**
 - Maps a patch feature p_i to text space and the projected feature is denoted as \hat{p}_i .
 - The learned pseudo-class name s_c is concatenated with normal prompt v^n (e.g. a normal s_c) and abnormal prompt v^a (e.g. a broken s_c).
 - The text encoder T outputs the normal text feature $t_{n,c} = T([v^n; s_c])$ and the abnormal text feature $t_{a,c} = T([v^a; s_c])$.
 - The semantic anomaly score of a patch p_i is $S_{sem}(p_i) = \frac{\exp(\hat{p}_i \cdot t_{a,c})}{\exp(\hat{p}_i \cdot t_{n,c}) + \exp(\hat{p}_i \cdot t_{a,c})}$.
 - Ground truth is 1 when $p_i = p_i^a$ and vice versa.
 - Binary cross entropy (BCE) loss is applied on each patch for training.

Inference

- During testing, RM anomaly score of a patch p_i is $S_{rec}(p_i) = \|p_i - RM(p_i)\|_2^2$.
 - When p_i is normal, $S_{RM}(p_i)$ is small
 - When p_i is abnormal, $S_{RM}(p_i)$ is large
- The SAD anomaly score and RM anomaly score are fused with a dataset specific hyperparameter λ .

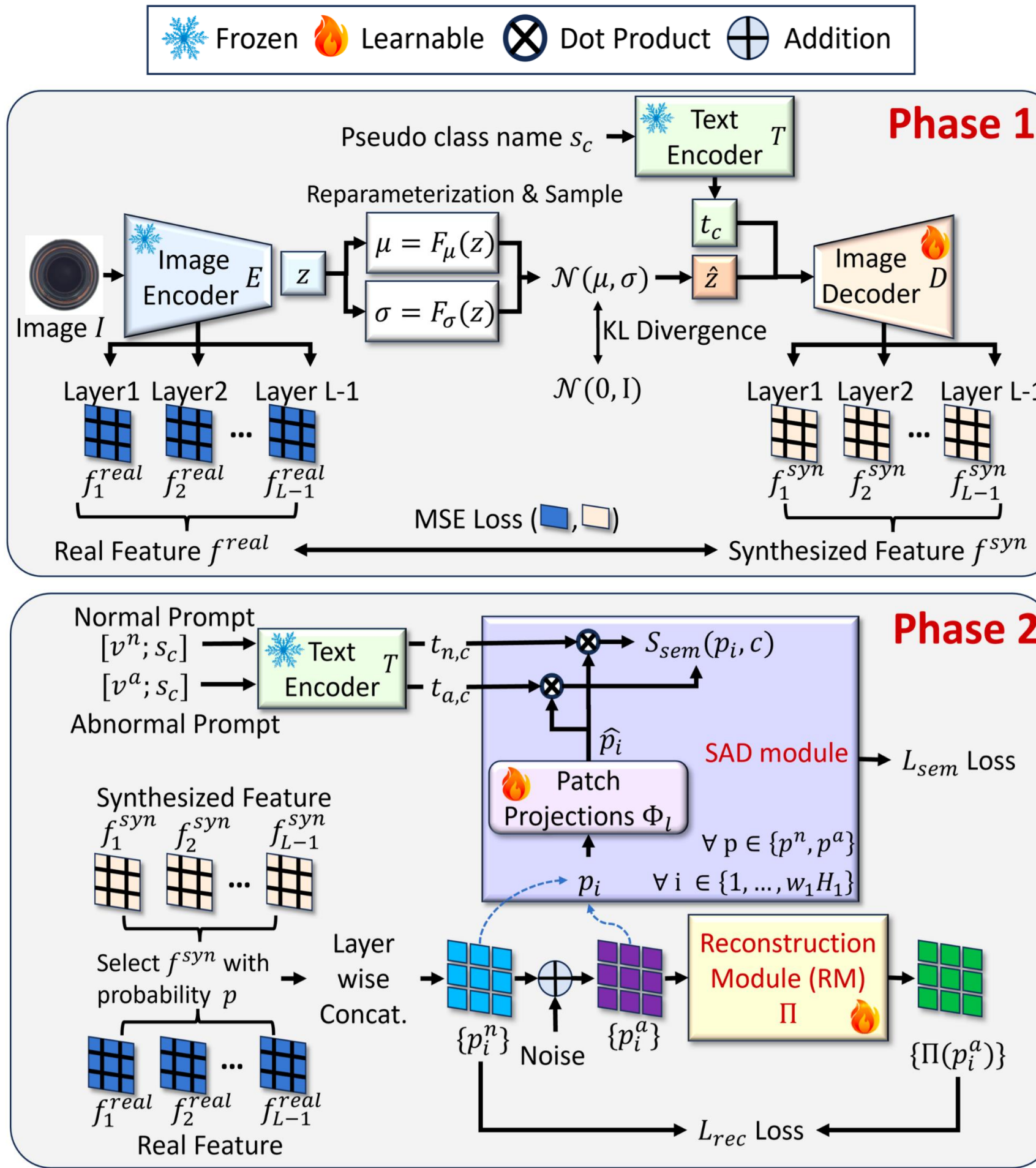


Fig 3. The proposed LTAD training contains Phase 1 (Top) and Phase 2 (Bottom).

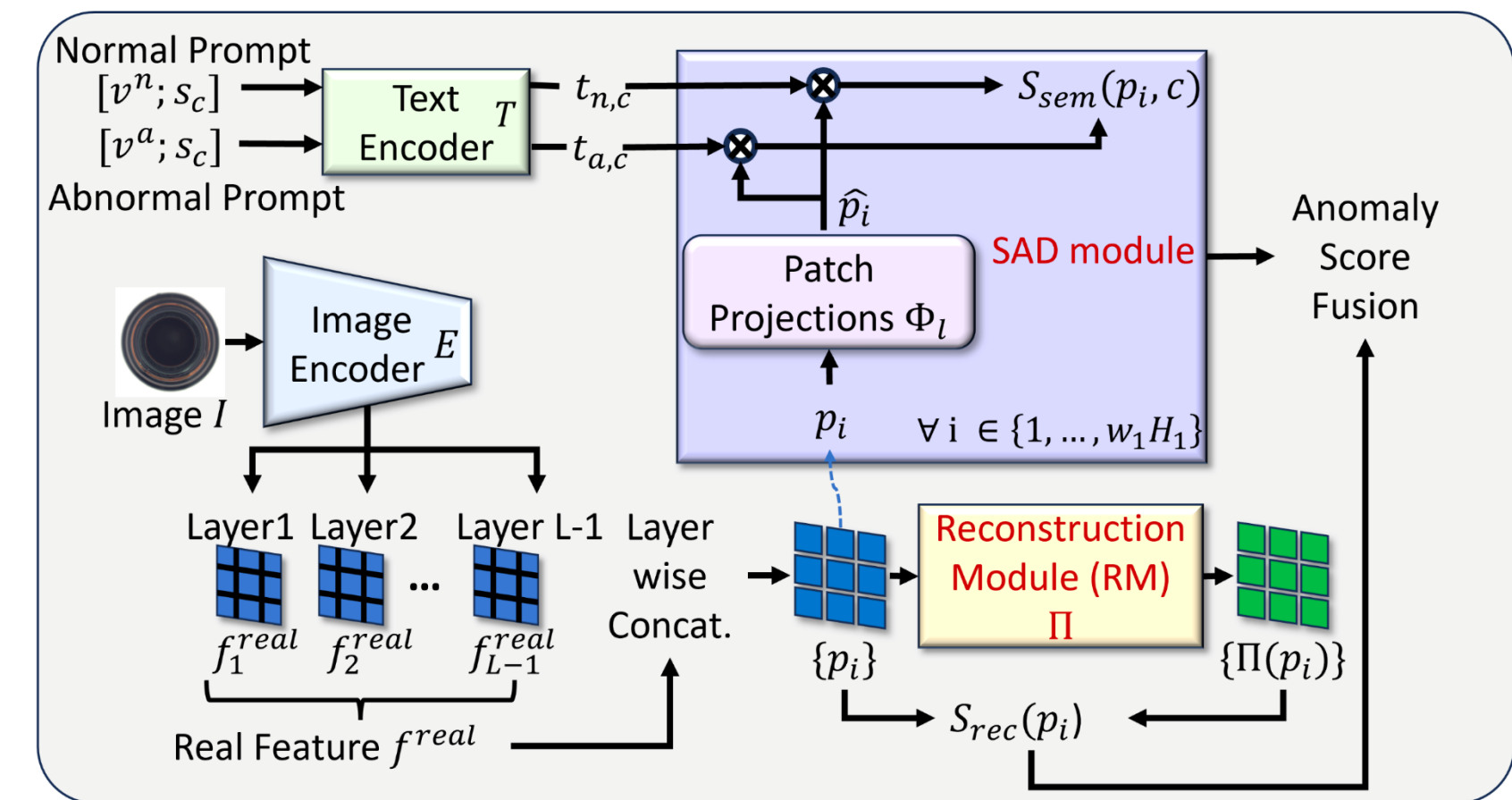


Fig 4. Inference stage of the proposed LTAD.

Experiment

Config.	Task	Cut & Paste	MKD	DRAEM	RegAD	UniAD	AnomalyGPT	LTAD w/o SAD	LTAD
exp100	Det.	75.89	78.92	79.57	82.43	87.70	87.44	88.74	88.86
	Seg.	N/A	85.95	85.17	95.20	93.95	89.68	94.00	94.46
exp200	Det.	75.07	79.93	78.82	N/A	86.21	85.80	86.94	86.05
	Seg.	N/A	86.01	82.95	N/A	93.26	90.15	93.40	94.18
step100	Det.	76.57	79.61	69.82	81.54	83.37	85.95	87.05	87.36
	Seg.	N/A	85.90	79.65	95.10	91.47	89.28	93.13	93.83
step200	Det.	76.53	79.31	71.64	N/A	81.32	82.47	85.33	85.60
	Seg.	N/A	86.03	76.79	N/A	89.29	89.45	91.78	92.12

Table 1. Quantitative result on MVTEC [1] dataset.

Config.	Task	RegAD	UniAD	AnomalyGPT	LTAD w/o SAD	LTAD
exp100	Det.	71.36	77.31	70.34	79.27	80.00
	Seg.	94.40	95.03	80.32	95.07	95.56
exp200	Det.	72.10	76.87	69.78	78.55	80.21
	Seg.	94.69	94.80	79.48	94.51	95.36
exp500	Det.	N/A	73.67	68.18	77.25	78.53
	Seg.	N/A	94.35	78.83	94.04	94.66
step100	Det.	71.80	78.83	71.98	82.80	84.80
	Seg.	94.99	96.04	82.30	96.16	96.57
step200	Det.	71.65	77.64	69.78	83.79	84.03
	Seg.	94.52	95.66	81.97	95.89	96.27
step500	Det.	N/A	71.84	62.88	82.42	83.33
	Seg.	N/A	95.03	81.48	95.50	96.41

Table 2. Quantitative result on VisA [4] dataset.

Table 3. Quantitative result on DAGM [5] dataset.

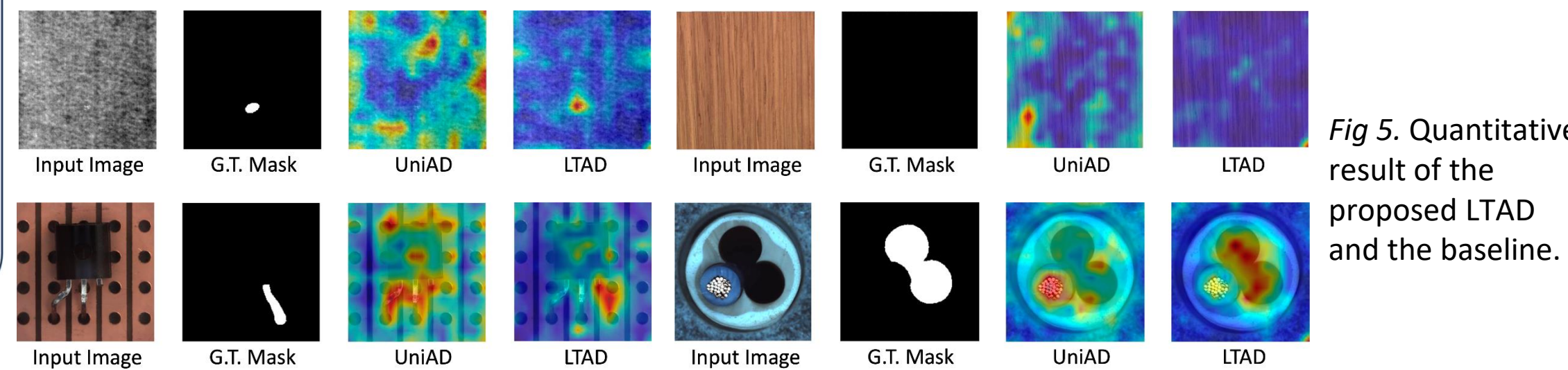


Fig 5. Quantitative result of the proposed LTAD and the baseline.

assign $s_{c=i}$ to class i	use text encoder T	Detection			Segmentation		
		All	High	Low	All	High	Low
✓	✓	72.76	81.06	65.49	63.74	62.09	65.18
✗	✗	59.79	63.34	56.69	69.83	70.95	68.85
✓	✓	84.12	97.02	72.84	91.36	95.13	88.07

Table 4. Importance of pseudo class name s_c on MVTEC-step100.

Table 5. Ablation on different normal/abnormal text prompts (i.e., v^a and v^n) on MVTEC step100.

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References

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